3D Photography

Wednesdays 09:30-11:30 – Room 3305 Ioannis Stamos

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Office: 1090G, Hunter North (Entrance at 69th bw/ Park and Lexington Avenues) Class website: http://www.cs.hunter.cuny.edu/~ioannis/3D_f11.html

Overview

- Create geometric and photometric 3D models
- Use Range and Image Sensing
- Fusing image data
- Comprehensive system with automation





3D Photography & Graphics



Modeling [Representation of 3D objects]
Rendering [Construction of 2D images from 3D models]
Animation [Simulating changes over time]

Applications

- Virtual environment generation
 - Google Earth
 - acquire model for use in VRML, entertainment, etc
 - Realistic sets: movies and video games
- Reverse engineering
 - acquiring a model from a part copying/modification
- Part inspection
 - compare acquired model to "acceptable" model
- 3D FAX
 - transmit acquired model to remote RP machine
- Architectural site modeling
- Urban Planning
- Historical Preservation and Archaeology
- Reverse Engineering of Buildings

M. Reed – Columbia University [3D Fax]



Industrial Inspection

• Determine whether manufactured parts are within tolerances



3D Modeling (people)



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3D PHOTOGRAPHY EXAMPLE

Buildings





Automatic registration. Each scan has a different color.

Registration details



3D PHOTOGRAPHY EXAMPLE

24 scans were acquired of façade of Shepard Hall (City College of NY)



Data Acquisition, Leica Scan Station 2, Park Avenue and 70th Street, NY



Art

 The Pietà Project IBM Research

- The Digital Michelangelo Project Stanford University
- The Great Buddha Project University of Tokyo







Photograph

Combined 3D mesh

(with P. K. Allen, Columbia University)



Inserting models in Google Earth



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3D Acquisition Pipeline



Main Topics

Data Acquisition and Representation







Segmentation





3D Modeling (Mesh or volumetric)







Model simplification



Passive techniques: Stereo and Structure from Motion

Augmented pin-hole camera model

- Focal point, orientation
- · Focal length, aspect ratio, center, lens distortion



2D ⇔ 3D correspondence "Classical" calibration



2D ⇔ 2D correspondence SFM, "Self-calibration"

3D range to 2D image registration



3D scene

2D image

3D range to 2D image registration



Texture mapped 3D model Corresponding 2D/proj. 3D lines

TEXTURE MAP ANIMATION



The Façade Modeling System



Symmetry Detection







Image-Based Rendering

- Chen and Williams (1993) view interpolation
- McMillan and Bishop (1995) plenoptic modeling
- Levoy and Hanrahan (1996) light field rendering





The graphics pipeline

the traditional pipeline



the new pipeline?



Slide courtesy Marc Levoy

Dynamic Scenes



Image sequence (CMU, Virtualized Reality Project) http://www.ri.cmu.edu/projects/project_144.html

Dynamic Scenes



Dynamic 3D model (CMU, Virtualized Reality Project) http://www.ri.cmu.edu/projects/project_144.html

Dynamic Scenes



Dynamic texture-mapped model (CMU, Virtualized Reality Project) http://www.ri.cmu.edu/projects/project_144.html

Libraries

- Open Inventor Graphics Libraries
- Coin3D implements Open Inventor API: <u>http://www.coin3d.org/</u>
- Online book:

http://www-evasion.imag.fr/Membres/Francois.Faure/doc/inventorMentor/sgi_html/

• **Book:** The Inventor Mentor : Programming Object-Oriented 3D Graphics with Open Inventor, Release 2