

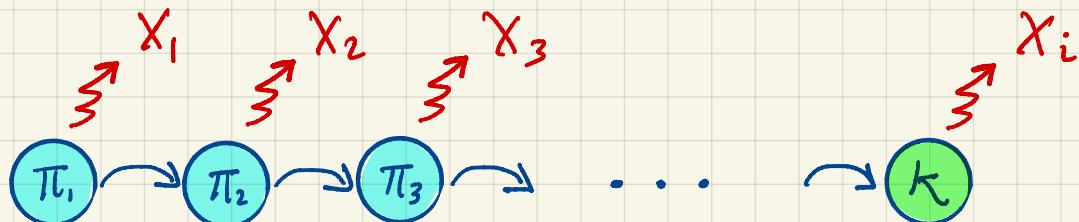
- Consider all possible paths
- Compute above probability for each path
- Identify the one with largest probability
- Correct, but NOT efficient.
- There are exponentially many paths, e.g. 2^n for our example.

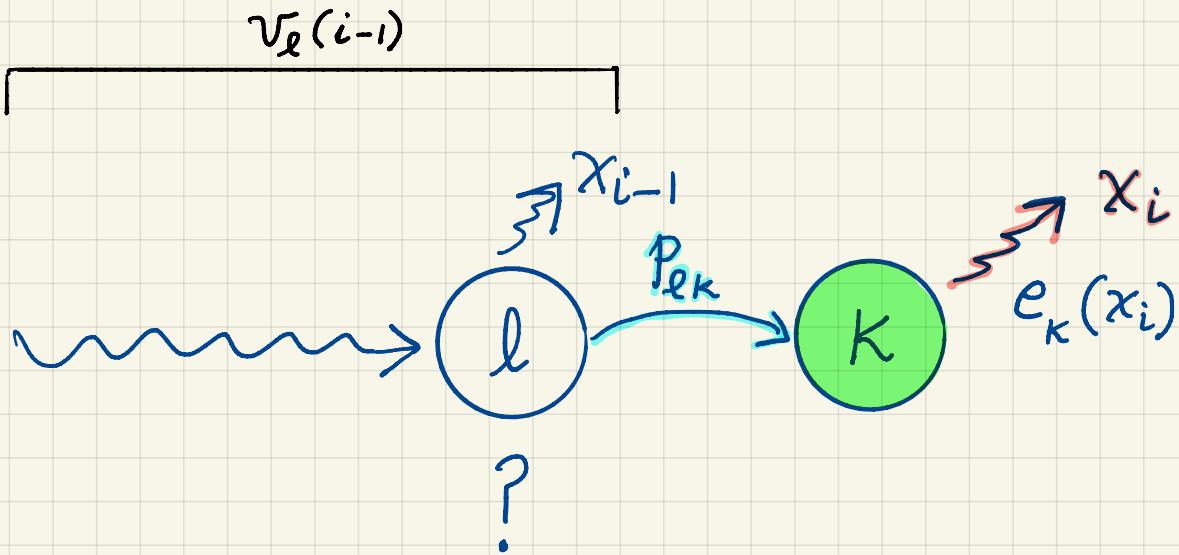
Solution: Viterbi algorithm.

Define $V_k(i) = \text{prob. of } \underline{\text{OPTIMAL}} \text{ path } \pi_1 \dots \pi_i$

that generates $x_1 \dots x_i$ and

ends in state k ($\pi_i = k$)





$$V_K(i) = \max_l [e_K(x_i) \cdot V_l(i-1) \cdot P_{lK}]$$

We can compute $V_K(i)$ if we have

$V_0(i-1), V_1(i-1), \dots, V_K(i-1)$ where $K = \# \text{states}$

Finally, we need $\max_K V_K(n)$

Viterbi

$$V_0(0) = 1 \quad V_k(0) = 0 \text{ for all } k \neq 0$$

$$V_k(i) = e_k(x_i) \max_{\ell} [V_{\ell}(i-1) P_{\ell k}]$$

$$\text{return } \max_k V_k(n)$$

Init
for $k = 0 \dots K$
do $V[k, 0] = 0$

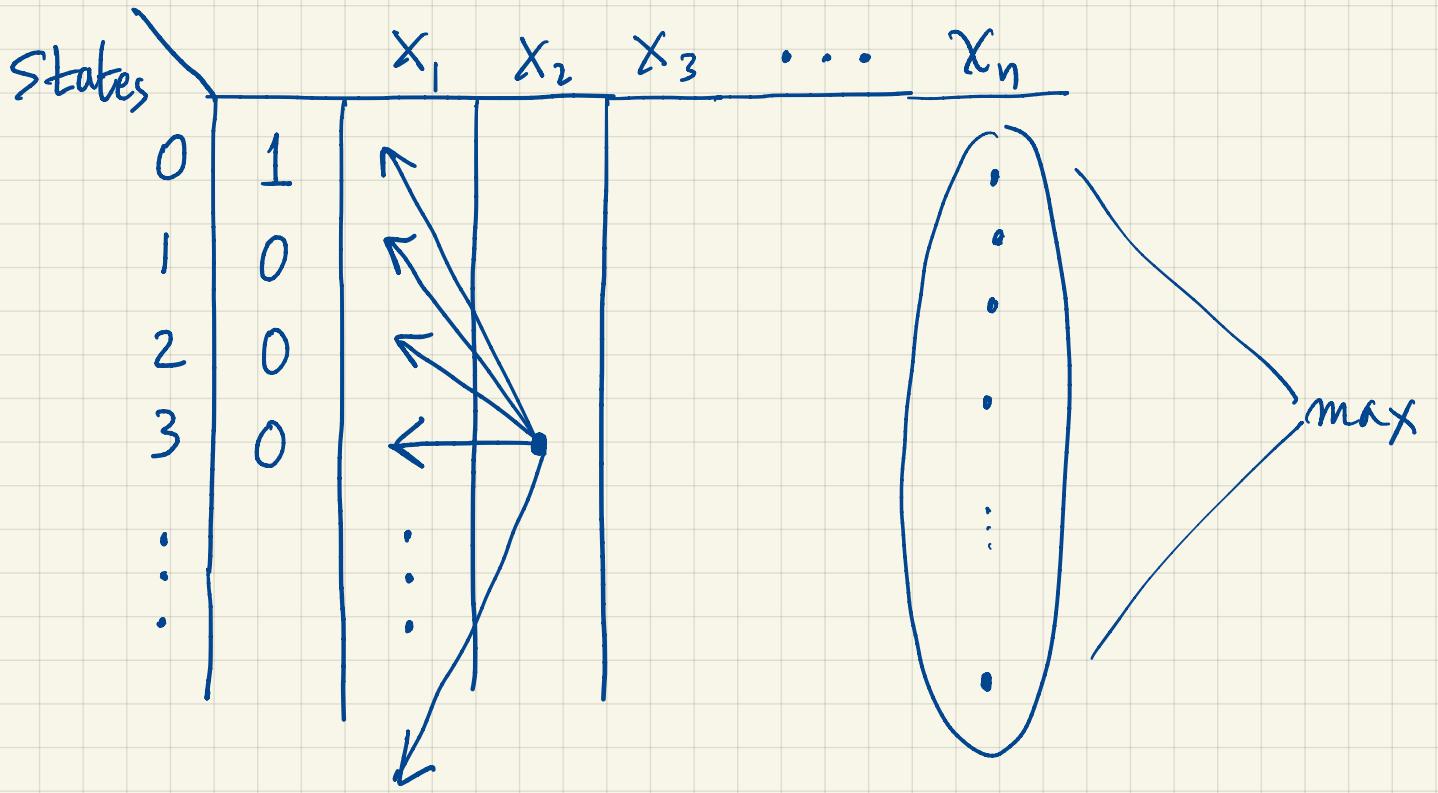
$$V[0, 0] = 1$$

for $k = 0 \dots K$
for $i = 1 \dots n$

$$V[k, i] = \underbrace{e_k(x_i) \cdot \max_{\ell} [V[\ell, i-1] \cdot P_{\ell k}]}_{\text{for loop to find max}}$$

$$V_0(0) = 1$$

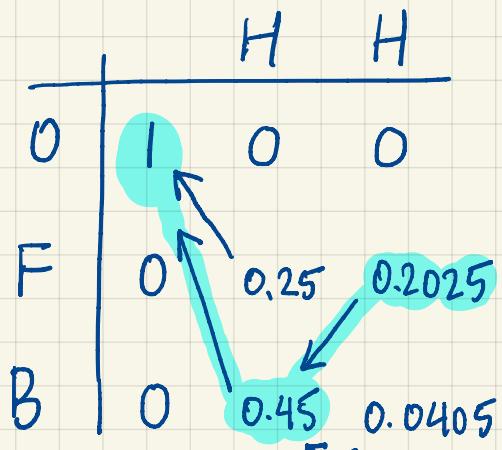
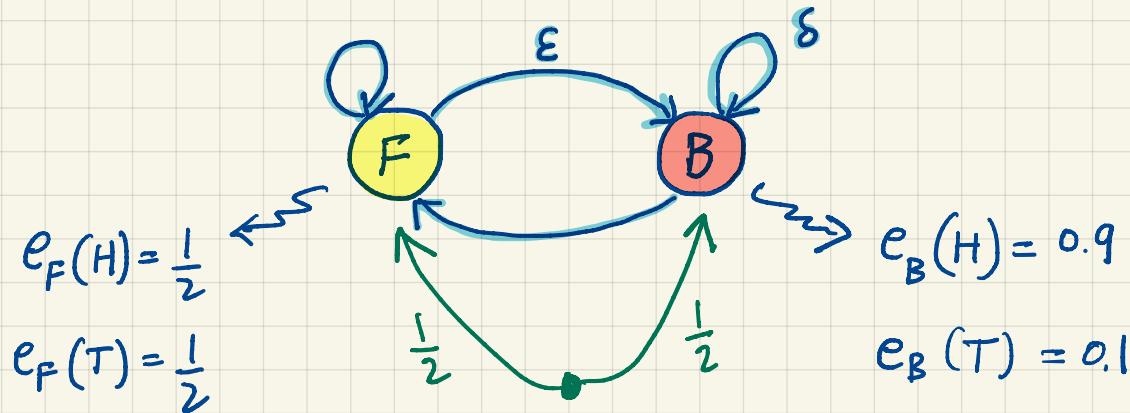
$$V_k(0) = 0 \text{ for } k \neq 0$$



$V_k(i)$ needs the previous column to be computed.

Time needed proportional to $n K^2$, $K = \# \text{ states}$.

Example : Assume $P_{OF} = P_{OB} = \frac{1}{2}$, $\epsilon = \delta = 0.1$



$$V_B(1) = \max \left\{ \begin{array}{l} e_B(H) V_O(0) P_{OB} \\ e_B(H) V_F(0) P_{FB} \\ e_B(H) V_B(0) P_{BB} \end{array} \right. = 0.9 \times 1 \times \frac{1}{2}$$

$$= 0.9 \times 0 \times 0.1$$

$$= 0.9 \times 0 \times 0.1$$

$$V_F(2) = \max \left\{ \begin{array}{l} e_F(H) V_O(1) P_{OF} \\ e_F(H) V_F(1) P_{FF} \\ e_F(H) V_B(1) P_{BF} \end{array} \right. = \frac{1}{2} \times 0 \times \frac{1}{2}$$

$$= \frac{1}{2} \times 0.25 \times 0.9$$

$$= \frac{1}{2} \times 0.45 \times 0.9$$

Practical Consideration

- Probabilities get too small ≈ 0 for large n .
- Problem with precision
- Use log space

$$V_k(i) = \log v_k(i)$$

$$E_k(b) = \log e_k(b)$$

$$P_{ek} = \log p_{ek}$$

Then

$$V_k(i) = E_k(b) + \max_b \left[V_k(i-1) + P_{ek} \right]$$

$$V_0(0) = 0 \quad V_k(0) = -\infty \text{ for } k \neq 0$$

What if we want the most probable state for a given i

In general

$$P(\pi_i = k \mid x_1, \dots, x_n) = \frac{P(x_1, \dots, x_n, \pi_i = k)}{P(x_1, \dots, x_n)}$$

First, let's consider $P(x_1, \dots, x_n)$ and focus on $P(x_1, \dots, x_i, \pi_i = k)$

Then $P(x_1, \dots, x_n) = \sum_k \underbrace{P(x_1, \dots, x_n, \pi_n = k)}_{f_k(n)}$

$f_k(i)$

Probability of generating x_1, \dots, x_i and ending in state k .

Similar recurrence to $\mathcal{V}_k(i)$: $f_k(i) = c_k(x_i) \sum_l f_l(i-1) p_{lk}$

Replace max with \sum

Forward:
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$$f_0(0) = 1 \quad f_k(0) = 0 \text{ for all } k \neq 0$$

$$f_k(i) = c_k(x_i) \sum_{\ell} f_{\ell}(i-1) P_{\ell k}$$

$$P(x_1 \dots x_n) = \sum_k f_k(n)$$

Now, let's look at  $P(x_1 \dots x_n, \pi_i=k)$

$$\underbrace{P(x_1 \dots x_i \overbrace{x_{i+1} \dots x_n}^B, \pi_i=k)}_A = P(\overbrace{x_1 \dots x_i, \pi_i=k}^A) P(\overbrace{x_{i+1} \dots x_n}^B | \overbrace{x_1 \dots x_i, \pi_i=k}^A)$$
$$= f_k(i) \cdot \underbrace{P(x_{i+1} \dots x_n | \pi_i=k)}_{b_k(i)}$$

Marko  
Property

$b_k(i)$  is the probability of generating  $x_{i+1} \dots x_n$  given we are in state  $k$  at time  $i$ .

$$b_k(i) = \sum_l P_{kl} e_l(x_{i+1}) b_l(i+1)$$

"backwards"

we need  $b_l(i+1)$  for all  $l$  to compute  $b_k(i)$

Backward:

$$b_k(n) = 1 \quad \text{for all } k$$

$$b_k(i) = \sum_l P_{kl} e_l(x_{i+1}) b_l(i+1)$$

$i = n-1 \dots 1$

Note  $b_0(0) =$

$$\sum_l P_{0l} e_l(x_1) b_l(1)$$

$$= P(x_1 \dots x_n)$$

Finally  $P(\pi_i = k \mid x_1, \dots, x_n) = \frac{f_k(i) b_k(i)}{\sum_k f_k(i) = b_0(0)}$