## Random variables (continuous)

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## 1 Defining probability density

A random variable X is a continuous random variable if its domain, i.e. the set of values x that X can take, is continuous. In this case, and analogous to the discrete case, we define a probability density function  $f_X(x)$  (as opposed to a probability mass function), which is a continuous function of x that captures the notion of probability in the following way:

$$P(a \le X \le b) = \int_{a}^{b} f_X(x) dx$$

We will drop the subscript X from  $f_X$  whenever it is clear from the context. Accordingly,

$$P(X = x) = \int_{x}^{x} f(y)dy = 0$$

for any single value x. This is because the domain of the random variable is now uncountable, and for the total probability to be 1, each single value must have 0 probability.

$$\int_{-\infty}^{\infty} f(x)dx = 1$$

Note that 0 is not really 0 in the sense that X = x could occur. For instance,

$$\frac{P(X=a)}{P(X=b)} = \frac{f(a)}{f(b)}$$

This can be seen from the following approximation. Let  $\delta$  be a small increment, then:

$$P(x \le X \le x + \delta) \approx f(x)\delta$$

Therefore,  $P(a \le X \le a + \delta)/P(b \le X \le b + \delta) \approx \frac{f(a)\delta}{f(b)\delta}$ . Taking the limit as  $\delta$  goes to 0, we have P(X=a)/P(X=b) = f(a)/f(b).

All the concepts that we have seen in the discrete case, carry over to the continuous case:

- Expectation:  $E[g(x)] = \int_{-\infty}^{\infty} g(x)f(x)dx$
- Independence: X and Y are independent  $\Leftrightarrow f_{X,Y}(x,y) = f_X(x)f_Y(y)$
- Conditional density:  $f_{X|Y}(x) = f_{X,Y}(x,y)/f_Y(y)$

To see why conditional probability is consistent with the new definition, consider  $P(x \le X \le x + \delta | y \le Y \le y + \delta)$  for a small increment  $\delta$ . We would like this probability to be approximately  $f_{X|Y}(x)\delta$ . But,

$$P(x \le X \le x + \delta | y \le Y \le y + \delta) = P(x \le X \le x + \delta, y \le Y \le y + \delta) / P(y \le Y \le y + \delta)$$

Therefore,

$$f_{X|Y}(x)\delta = \frac{f_{X,Y}(x,y)\delta^2}{f_Y(y)\delta}$$

Taking the limit as  $\delta$  goes to 0 gives the desired definition for  $f_{X|Y}(x)$ .

With this definition for conditional probability, Bayes' rule for a continuous random variable becomes:

$$f_{X|Y}(x) = \frac{f_{X,Y}(x,y)}{f_{Y}(y)} = \frac{f_{Y|X}(y)f_{X}(x)}{f_{Y}(y)}$$

Note  $f_Y(y)$  can be expressed as an integral in the same way P(Y=y) can be expressed as a sum  $\sum_x P(Y=y|X=x)P(X=x)$  in the discrete case. Therefore,

$$f_Y(y) = \int f_{Y|X}(y) f_X(x) dx$$

Rewriting Bayes' rule, we have:

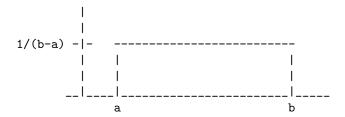
$$f_{X|Y}(x) = \frac{f_{Y|X}(y)f_X(x)}{\int f_{Y|X}(y)f_X(x)dx}$$

We often use the simplified notation f(y|x) to mean  $f_{Y|X}(y)$ . In this way, we can drop the subscript from f as it can be inferred from the its argument. Therefore,

$$f(x|y) = \frac{f(x,y)}{f(y)} = \frac{f(y|x)f(x)}{\int f(y|x)f(x)dx}$$

## 2 Example of breaking a stick twice

The (continuous) uniform distribution is given by the following density function.

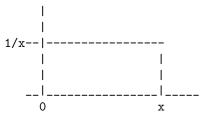


$$\int_{a}^{b} \frac{1}{b-a} dx = \frac{x}{b-a} \Big|_{a}^{b} = \frac{b}{b-a} - \frac{a}{b-a} = 1$$

Hold a stick of length l and break it uniformly at random, then repeat for the remaining part. Let X represent the first breaking point, then f(x) = 1/l (uniform from 0 to l).



Similarly, f(y|x) = 1/x (also uniform from 0 to  $x \le l$ ).



What is f(x,y)? From the definition:

$$f(x,y) = f(x)f(y|x) = \frac{1}{lx}, \qquad 0 \le y \le x \le l$$

Note that

$$\int_0^l \int_0^x \frac{1}{lx} dy dx = \int_0^l \frac{1}{l} dx = 1$$

We could have also evaluated the double integral in the other order:

$$\int_{0}^{l} \int_{y}^{l} \frac{1}{lx} dx dy = \int_{0}^{1} \frac{1}{l} \log x \Big|_{y}^{l} dy = \int_{0}^{l} \frac{1}{l} \log(l/y) dy = 1 \text{ (not showing the work)}$$

Note how the bounds of the inner integral change depending on which variable is integrated first. Note also that after integrating once, in the first case, we obtain f(x), and in the second case we obtain (what should be) f(y). This is always true: f(x,y) is called the joint density, and f(x) and f(y) are called the marginal densities. Note that  $\int f(x,y)dx$  is nothing but  $\int f(y|x)f(x)dx = f(y)$ . As we have seen before, this phenomenon is also true in the discrete case but is exhibited as a sum instead.

We conclude that

$$f(y) = \int_{y}^{l} \frac{1}{lx} dx = \frac{1}{l} \log(l/y), \qquad 0 \le y \le l$$

Computing expectations, E[X] = l/2 (easy). However, computing E[Y] involves computing the integral  $\int_0^l (y/l) \log(l/y) dy$ , which is not very difficult, but let's use conditional expectation instead:  $E[Y] = E_x[E_y[Y|X=x]] = E_x[x/2] = 1/2 \cdot E_x[x] = l/4$  (much easier to compute).

For another example of expectation, let us compute E[XY].

$$E[XY] = \int_{0}^{l} \int_{0}^{x} xyf(x,y)dydx = \int_{0}^{l} \int_{0}^{x} \frac{y}{l}dydx = l^{2}/6$$

We can also reach the same result using nested expectation.

$$E[XY] = E[E[XY|X]] = E[XE[Y|X]] = E[X^2/2] = \int_0^l \frac{x^2}{2l} dx$$

The second equality follows from the fact that conditioned on X, E[XY|X] = XE[Y|X] because X acts as a constant.

Finally, in the spirit of Bayes, we can now ask the following? What is f(x|y)? The importance of this lies in the following: given that we observe what is left of the stick, what can we say about how it was broken first?

$$f(x|y) = \frac{f(y|x)f(x)}{f(y)} = \frac{1/lx}{1/l \cdot \log(l/y)} = \frac{1}{x \log(l/y)}, \quad y \le x \le l$$

Let us interpret this result. If y=l, then  $f(x|y)=1/(0\cdot x)$  for  $l\leq x\leq l$ . This means the entire mass is located at x=l. This is obviously true since that's the only way we could have ended up with the entire stick. If y=0, then f(x|y)=0/x for  $0\leq x\leq l$ , which is 0 for every x except when x=0. This means that the entire mass is located at x=0, which is again the only way we could have ended up with no stick at all. Note that in both cases, the integral of this mass is still 1 at the limit.